

IC EXCESS CURRENT DETECTION SCHEME

FIELD OF THE INVENTION

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The present invention is generally related to the field of mass storage devices including a hard disk drive (HDD) controllers, and more particularly to detecting excess current on servo driver IC's.

10 BACKGROUND OF THE INVENTION

Servo driver integrated circuits (IC's) are typically used in mass storage devices including hard disk drive (HDD) control circuits for controlling a spindle motor.

Occasionally, excess current conditions to the spindle motor can cause damage to the
15 servo driver, and may also produce excess heat and cause a fire hazard. Conserving die space and minimizing power consumption is a key design criteria for these servo driver IC's.

There is desired an improved servo driver IC capable of detecting excess current
20 of servo drive IC that can facilitate reducing the excess IC current. There is also desired a small protection circuit that can eliminate the excess current condition.

SUMMARY OF THE INVENTION

The present invention achieves technical advantages by detecting excess current on any IC including a servo driver IC and preventing the disruptive damage which can be caused by the excess current. Typically, an isolation (Iso) FET is part of the servo driver IC. A detection circuitry having only a small silicon area is added whereby the detection circuit is independent of the Iso FET current path, being in parallel rather than in series. The detection circuitry also allows production tests on much smaller current thresholds.

10 BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a block schematic drawing of the present invention including means for sensing and reducing an overcurrent condition on a HDD controller; and

15 Figure 2 is a detailed schematic diagram illustrating one preferred implementation of the invention shown in Figure 1.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

20 Referring now to Figure 1, there is shown generally at 10 an overcurrent detection circuit according to the present invention. Current through an isolation FET (Iso FET) 12 is measured and compared with a replica Sense FET 14 at the drains thereof, with the ratio current flowing through the sensing FET 14 setting the detection threshold. Motor current I_{cc} flowing through the Iso FET 12 represents the total supply current from power supply V_{cc} . Voltage V_{pump} provides a voltage doubler voltage, and the variable Bias Current is digitally programmable through register bits of control circuitry (not shown) to select different detection levels for nominal operation and production tests.

A comparator 16 compares the two drain voltages of the Iso FET 12 and the Sense FET 14, which comparator 16 in turn compares the I_{cc} motor current with the threshold current and responsively generates an overcurrent fault signal OC to invoke further actions by the control circuitry to responsively reduce the I_{cc} current. In the case of a disk drive spindle motor driver IC, the spindle motor will brake for the remaining Pulse Width Modulation (PWM) duty cycle whenever an overcurrent fault occurs upon the assumption that a phase-to-ground short exists.

It's essential to quickly detect excess current on all servo driver IC's and to prevent the disruptive damage which could be caused by the excess current. Typically, the Iso FET 12 is already part of a servo driver IC, and the detection circuitry silicon area added is very small. Also, the detection circuit 10 is independent of the Iso FET 12 current path, and is in parallel rather than in series therewith. Detection circuit 10 also allows production tests on the much smaller current thresholds

For reference, node N1 is at the drain of Isolation (Iso) FET 12 and is coupled to the negative input to the comparator, and node N2 is at the drain of sense FET 14 and is coupled to the positive input to the comparator.

Voltage V_{pump} is the chip supply voltage multiplier, and is usually a voltage doubler as shown. Voltage V_{pump} is used to pull the gate of Iso FET 12 and Sense FET 14 hard so that the resistance across Iso FET 12 and Sense FET 14 is small. Voltage V_{pump} is usually readily available on the servo IC.

The Iso FET 12 is an on-chip DMOS transistor used as the passing/isolation FET. With its gate tied to voltage V_{pump} , the Iso FET 12 operates in the linear region and behaves like a resistor. On-chip Iso FET 12 is commonly required in a servo application.

The Sense FET 14 is a scaled down DMOS transistor matched to the Iso FET 12. It is also operated in the linear region and thus behaves like a resistor, with the resistance being inversely proportional to the ratio of the size between Iso FET 12 and Sense FET 14.

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The Variable Bias Current on-chip variable bias current is derived from the on-chip bandgap voltage divided by an external precision resistor, (not shown), and is digitally programmable through a serial port interface. The Variable Bias Current is desirable for production test at a smaller I_{cc} and to calibrate out the comparator 16 offset which contributes a large portion of error of the detection threshold accuracy. Production trimming is also implemented in the Variable Bias Current section to set an accurate detection threshold.

The Comparator 16 compares the two voltages at the drains (nodes N1 and N2) of the Iso FET 12 and the Sense FET 14. The Variable Bias Current along with Sense FET 14 (behaving like a resistor) creates a voltage drop from V_{cc} to the drain of the Sense FET 14, which is the positive input to the comparator 16, and that voltage drop sets the comparison threshold. Because the two FETs are ratioed, the detection threshold becomes:

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$$((\text{Iso FET size}) / (\text{Sense FET size})) * (\text{Current set at Variable Bias Current}).$$

When the excess current condition occurs (when I_{cc} becomes larger than the threshold), the drain of Iso FET 12 will be pulled lower than the threshold set at the positive input of the comparator 16, and thus, the comparator 16 output OC will transition from low to high. An OC "HIGH" state indicates the chip draws too much current. A delay in time is advantageously added in the comparator 16 to filter out any transient current spikes through the Iso FET 12. For the servo IC, the idea is to ignore current spikes caused by the spindle driver (not shown in the figure) negative flyback during

normal PWM operation, and to detect only a short from the spindle three phases to ground or any other illegal operation that draws excess current.

When an excess current is detected, the comparator 16 output OC transitions from low to high. Subsequent actions must be taken to reduce the current before the chip is damaged, or even worse, excess current generates excess heat and eventually the part could burn and cause a fire hazard. This invention can be part of a UL protection scheme. This circuit may also reduce the spindle current upon an OC fault.

10 Voltage at drain of Sense FET, node N2:

$$\begin{aligned} V_{N2} &= V_{CC} - R * I_{VBC} \\ &= V_{CC} - k * I_{VBC} / \text{Sense FET size} \end{aligned}$$

15 Where k is a constant, and I_{VBC} is the variable bias current.
The Sense FET 14 size is equivalent to the width of the transistor.

Voltage at drain of Iso FET, N1:

$$\begin{aligned} 20 \quad V_{N1} &= V_{CC} - R^1 * I_{CC} \\ &= V_{CC} - \frac{k * I_{CC}}{\text{Iso FET size}} \end{aligned}$$

The threshold of the comparator 16 is when the two input voltages are equal:

$$V_{N1} = V_{N2}$$

$$V_{CC} - \frac{k * I_{CC}}{Iso\ FET\ size} = V_{CC} - \frac{k * I_{VBC}}{Sense\ FET\ size} \quad \text{or:}$$

$$5 \quad I_{CC} = \frac{Iso\ FET\ size}{Sense\ FET\ size} * I_{VBC}$$

Though the invention has been described with respect to a specific preferred embodiment, many variations and modifications will become apparent to those skilled in the art upon reading the present application. It is therefore the intention that the appended

10 claims be interpreted as broadly as possible in view of the prior art to include all such variations and modifications.